

Probability and Random Processes

ECS 315

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10 Continuous Random Variables



Office Hours:

BKD, 6th floor of Sirindhralai building

Wednesday 14:30-15:30

Friday 14:30-15:30

Probability and Random Processes

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10.1 Probability Density Function

Ex. rand function

- Generate an array of uniformly distributed pseudorandom numbers.
 - The pseudorandom values are drawn from the **standard uniform distribution** on the open **interval (0,1)**.
- `rand` returns a scalar.
- `rand(m,n)` or `rand([m,n])` returns an *m*-by-*n* matrix.
 - `rand(n)` returns an *n*-by-*n* matrix

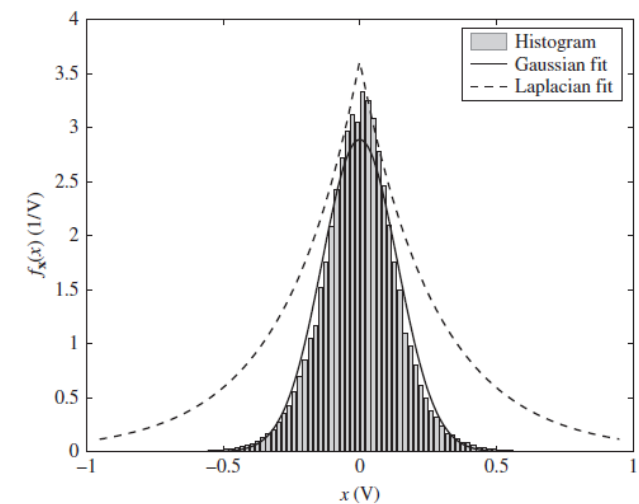
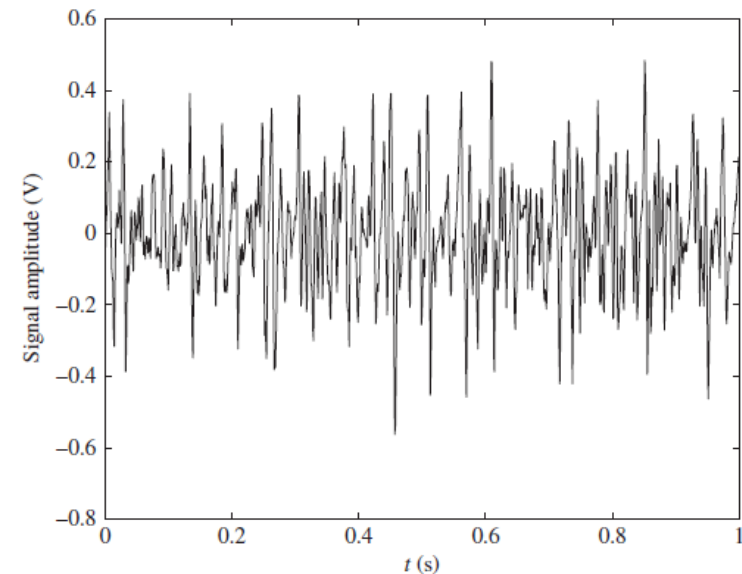
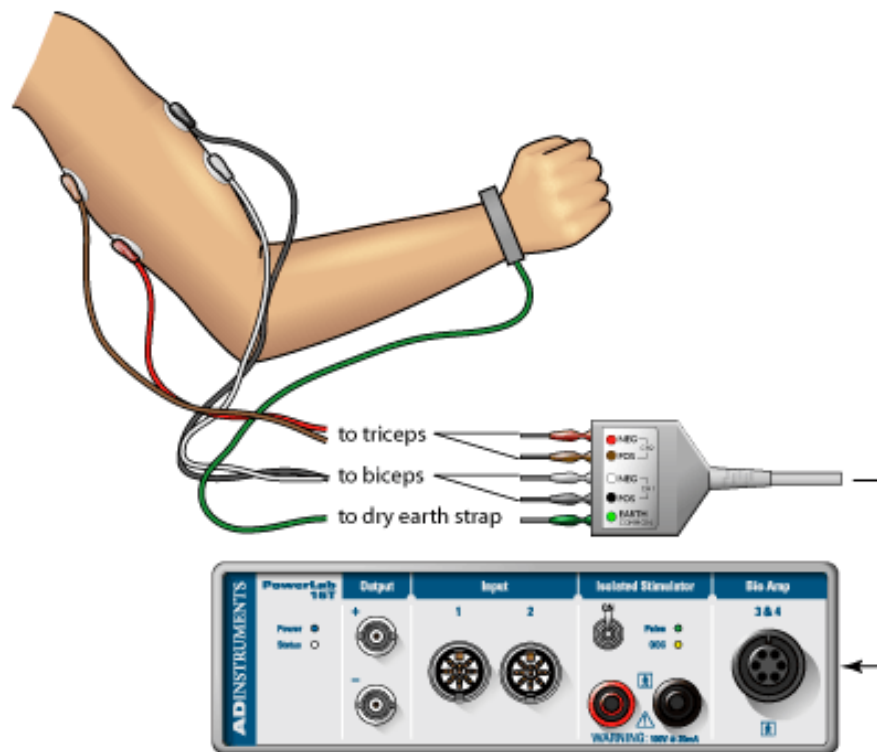
```
>> rand
ans =
    0.3816

>> rand(10,2)
ans =
    0.7655    0.6551
    0.7952    0.1626
    0.1869    0.1190
    0.4898    0.4984
    0.4456    0.9597
    0.6463    0.3404
    0.7094    0.5853
    0.7547    0.2238
    0.2760    0.7513
    0.6797    0.2551
```



Ex. Muscle Activity

- Look at electrical activity of skeletal muscle by recording a human electromyogram (EMG).

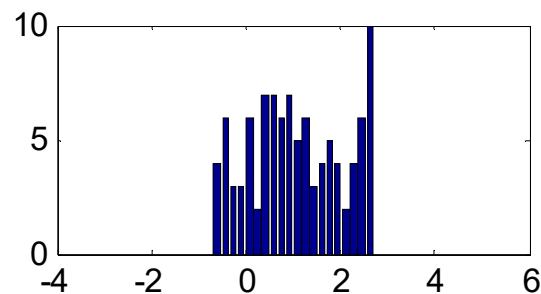
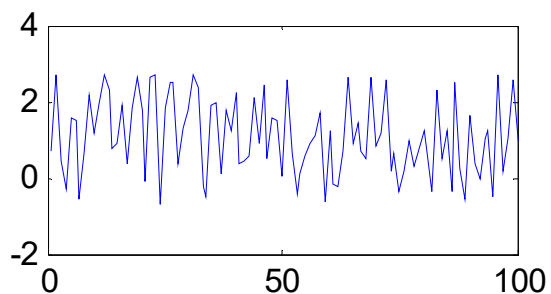


Three Important Continuous RVs

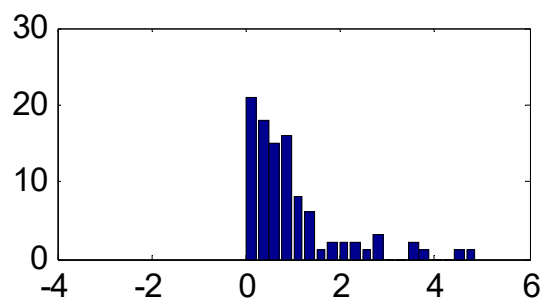
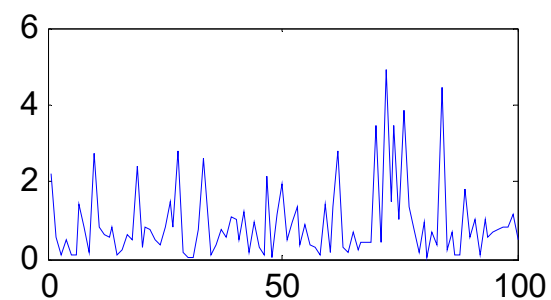
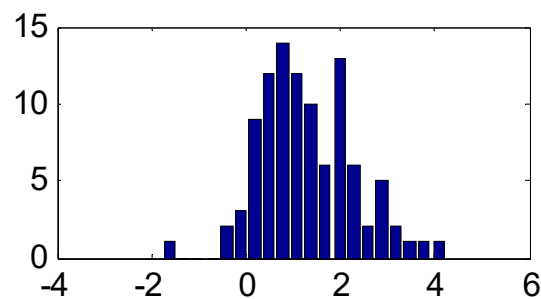
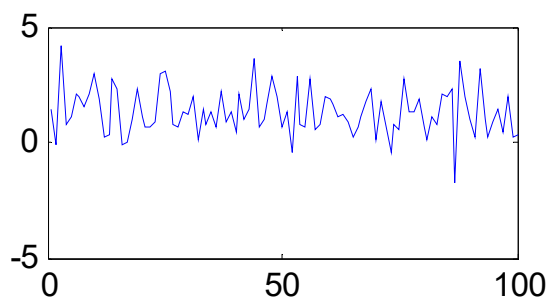
```
close all; clear all;
N = 1e6; b = 20; m = 1; s = 1;
R = [1-5*s,1+5*s];
% Uniform
X = (2*sqrt(3)*(rand(1,N)-0.5))+1;
subplot(3,2,1); plot(X);
subplot(3,2,2); plotHistPdf(X,b)
xlim(R)
% Normal
X = randn(1,N)+1;
subplot(3,2,3); plot(X);
subplot(3,2,4); plotHistPdf(X,b)
xlim(R)
% Exponential
X = exprnd(1,1,N);
subplot(3,2,5); plot(X);
subplot(3,2,6); plotHistPdf(X,b)
xlim(R)
```



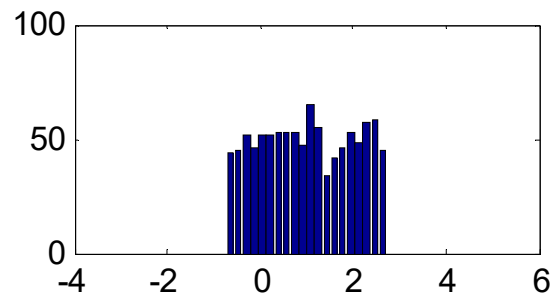
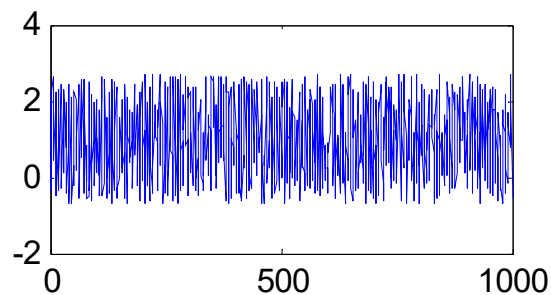
Three Important Continuous RVs



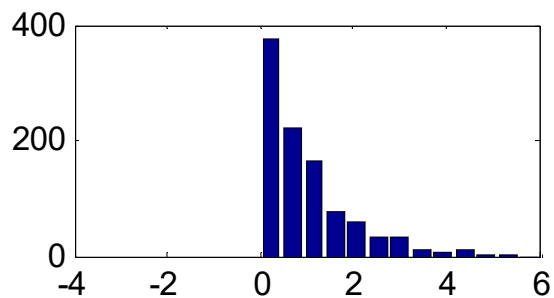
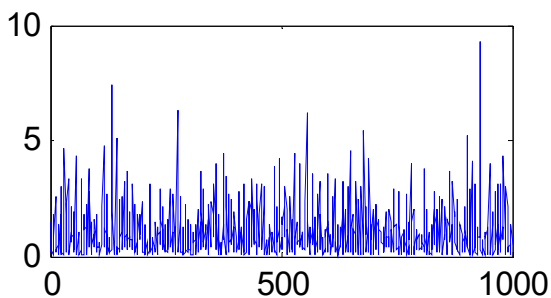
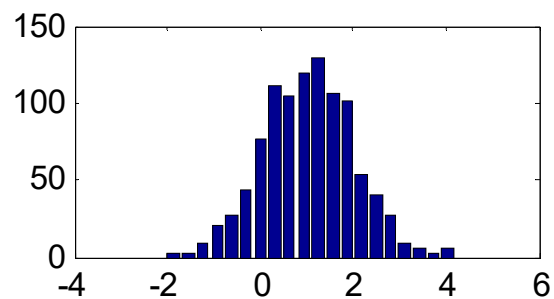
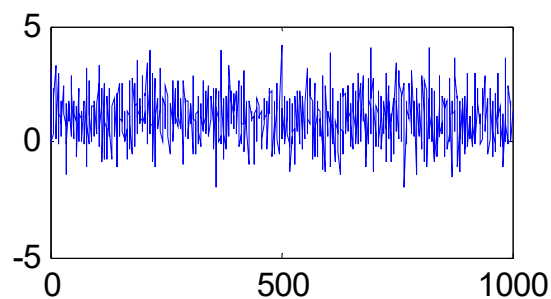
Mean = 1
Std = 1
N = 100



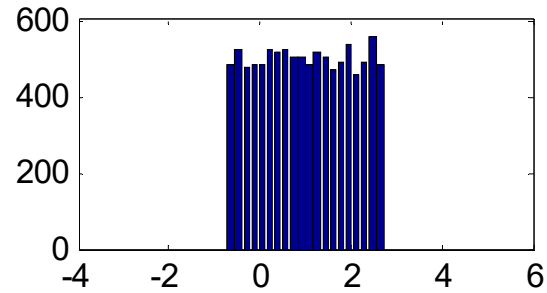
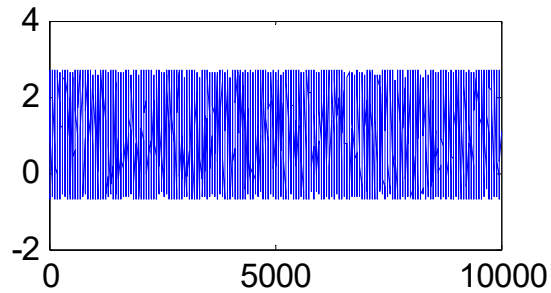
Three Important Continuous RVs



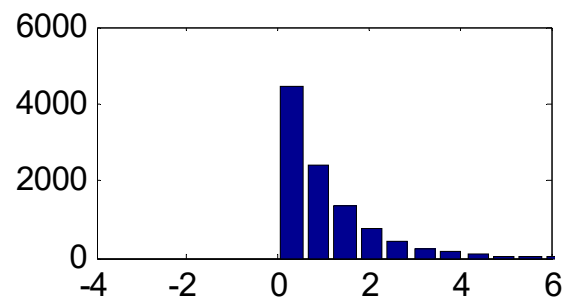
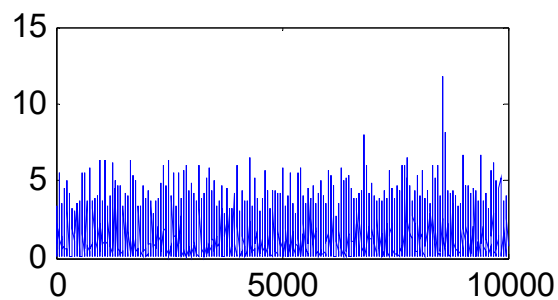
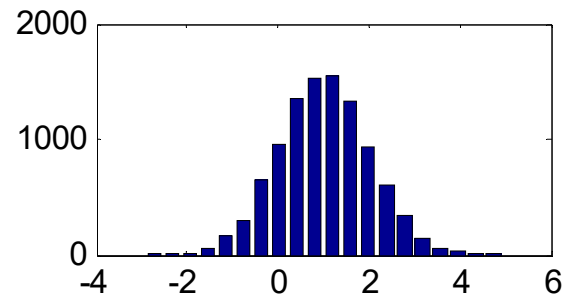
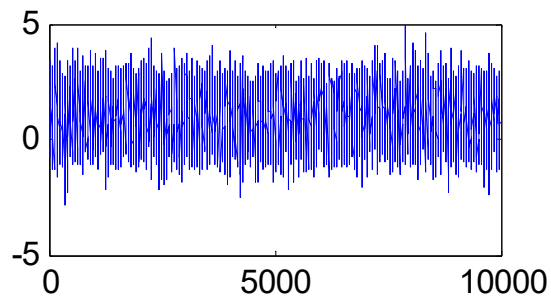
Mean = 1
Std = 1
N = 1,000



Three Important Continuous RVs



Mean = 1
Std = 1
N = 10,000



Review: $P[\text{some condition(s) on } X]$

For discrete random variable,

8.13. Steps to find probability of the form $P[\text{some condition(s) on } X]$ when the pmf $p_X(x)$ is known.

- (a) Find the support of X .
- (b) Consider only the x inside the support. Find all values of x that satisfy the condition(s).
- (c) Evaluate the pmf at x found in the previous step.
- (d) Add the pmf values from the previous step.

$$P[\text{some condition(s) on } X] = \sum p_X(x)$$

Discrete RV

Sum over all the x values that satisfy the condition(s)



$P[\text{some condition(s) on } X]$

- For discrete random variable,

$$P[\text{some condition(s) on } X] = \sum \overbrace{p_X(x)}^{\text{probability mass function (pmf)}}$$

Discrete RV

Sum over all the x values that satisfy the condition(s)

- For continuous random variable,

$$P[\text{some condition(s) on } X] = \int \overbrace{f_X(x) dx}^{\text{probability density function (pdf)}}$$

Continuous RV

Integrate over all the x values that satisfy the condition(s)

pmf \rightarrow pdf
 $\sum \rightarrow \int$



Support of a RV

- In general, the **support** of a RV X is any set S such that

$$P[X \in S] = 1.$$

- In this class, we try to find the smallest (minimal) set that works as a support.

- **For discrete random variable,**

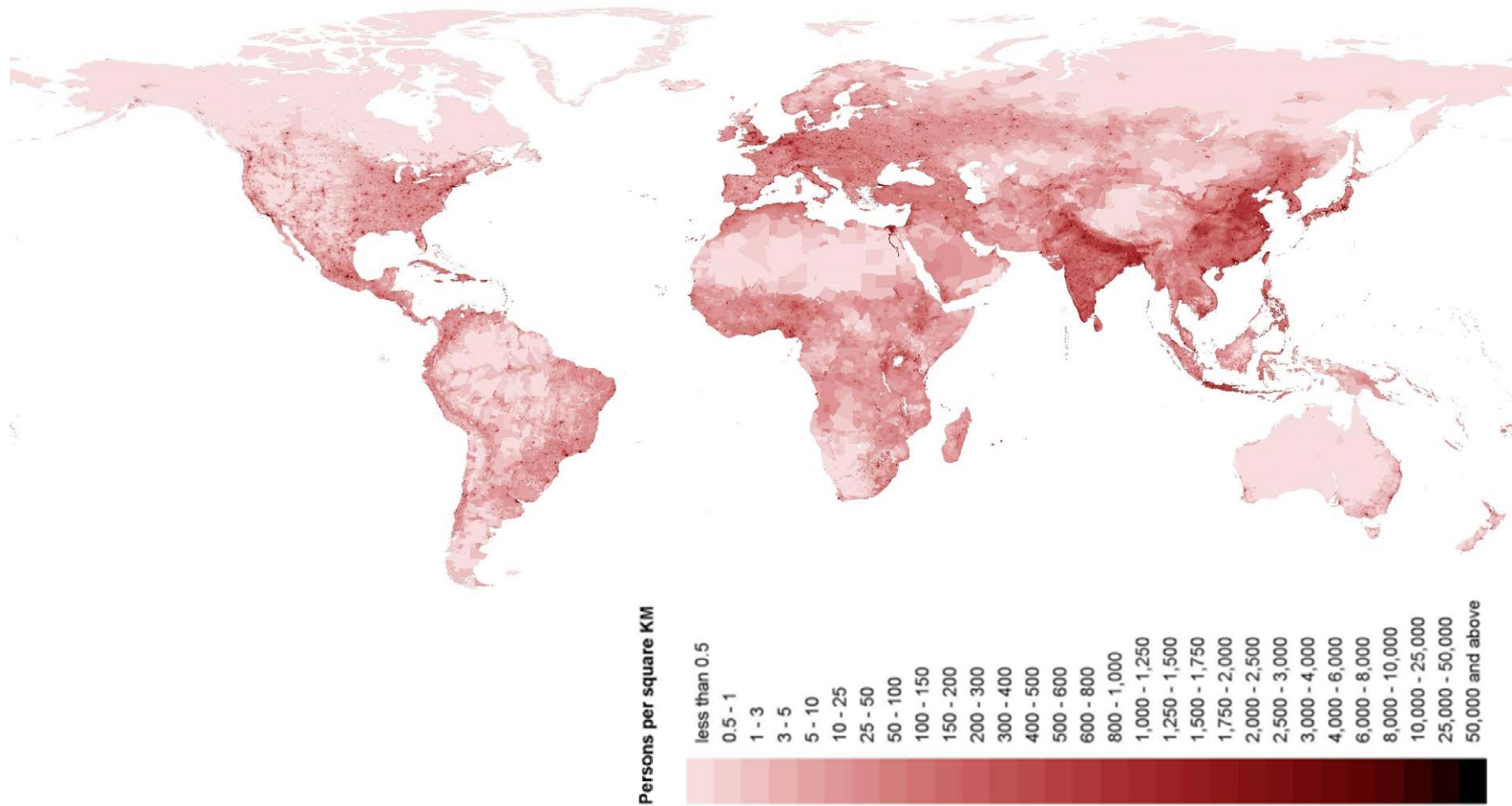
$$S_X = \{x: p_X(x) > 0\}$$

- **For continuous random variable,**

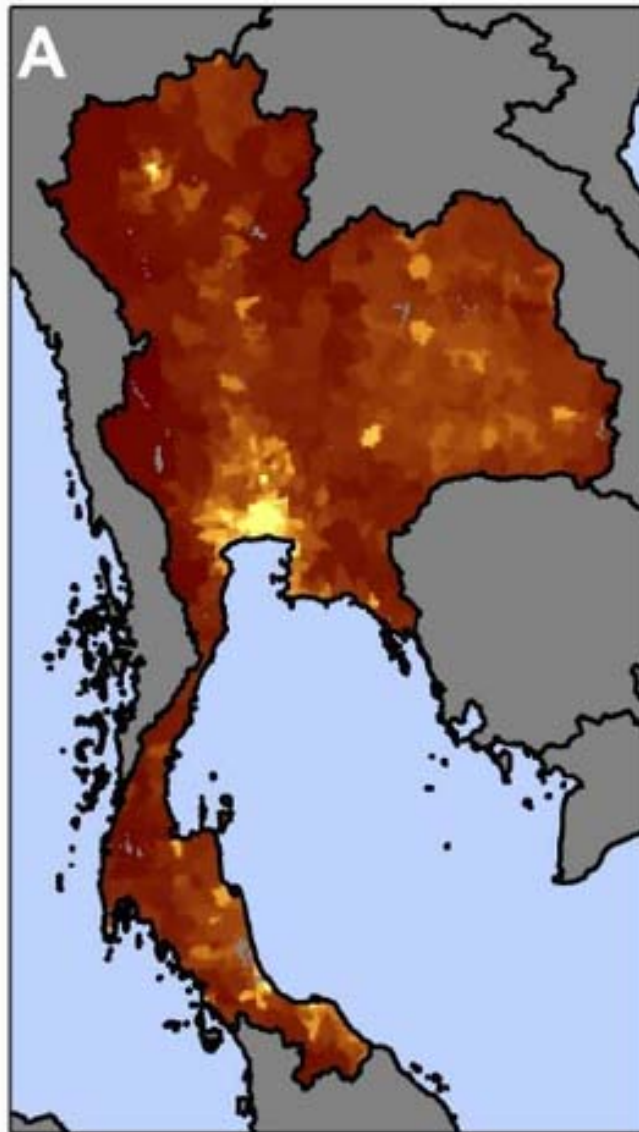
$$S_X = \{x: f_X(x) > 0\}$$



World Map of Population Density



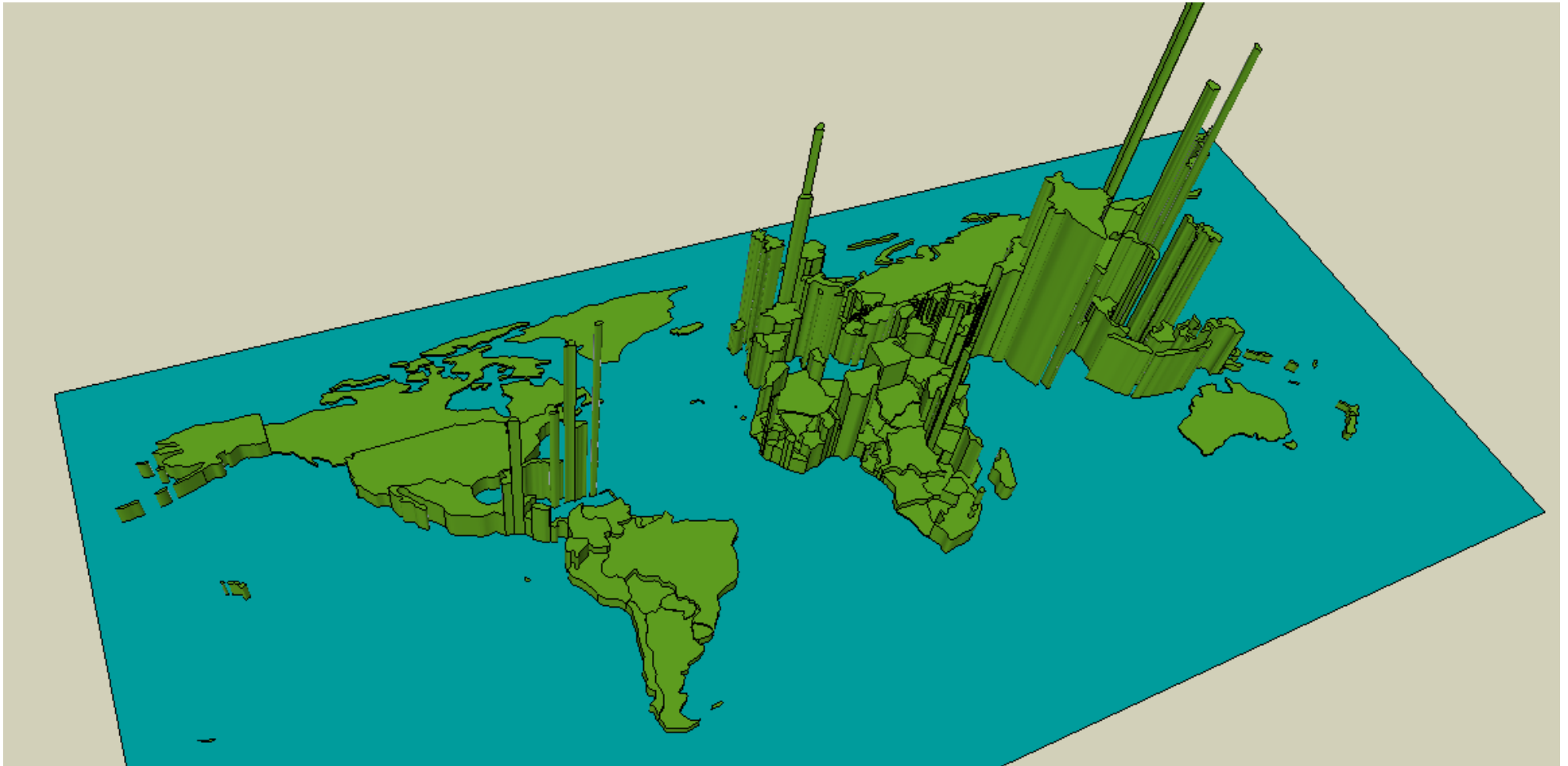
Thailand's Population Density



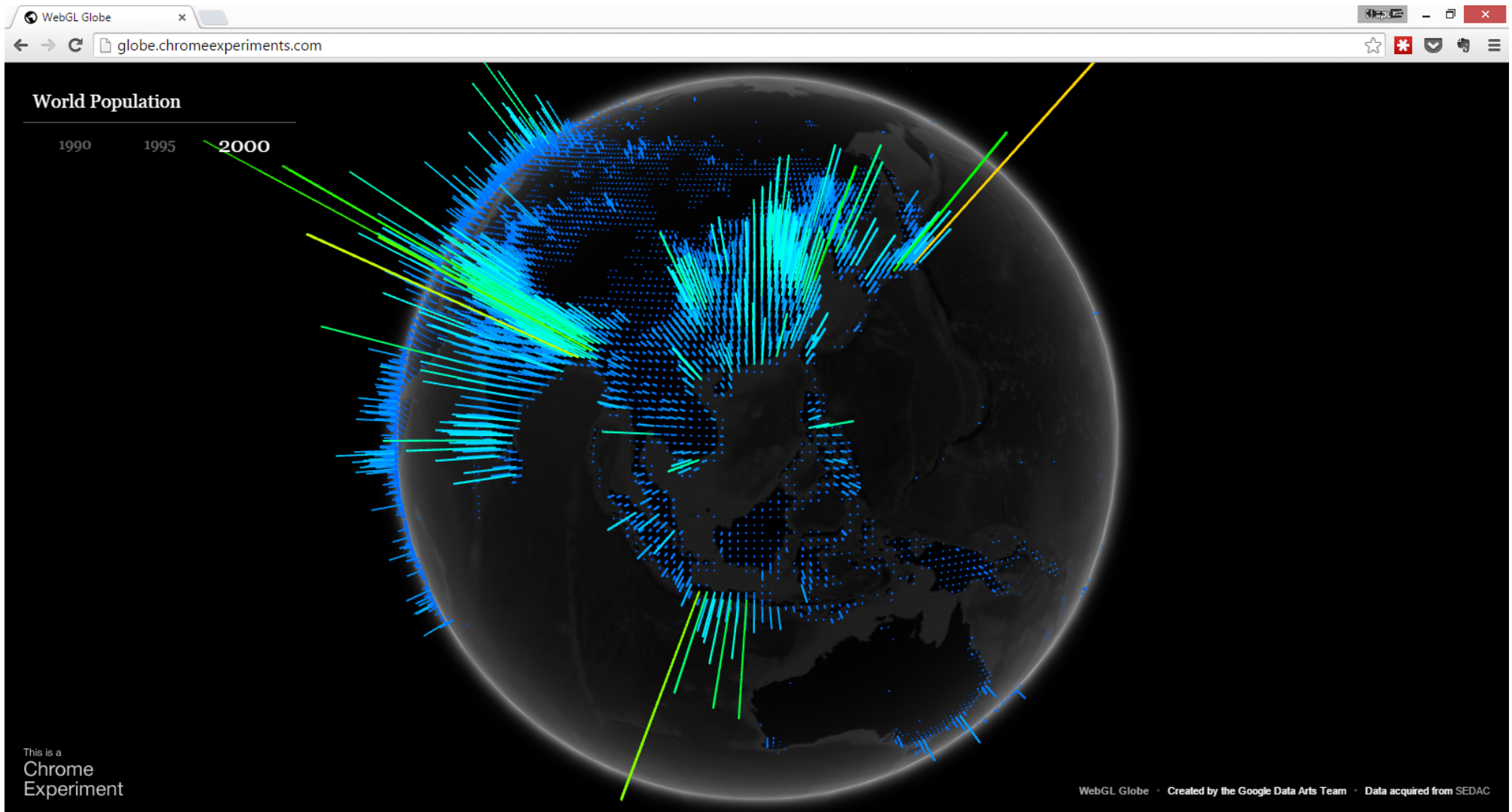
https://www.researchgate.net/publication/260378246_Climate-Related_Hazards_A_Method_for_Global_Assessment_of_Urban_and_Rural_Population_Exposure_to_Cyclones_Droughts_and_Floods/figures?lo=1



World Map of Population Density



World Map of Population Density



“Density”

- Density = quantity per unit of measure.
- Population Density = number of people per unit area
 - Location with high density value means there are a lot of people around that location.
 - Given a region, we integrate the density over that region to get the number of people residing in that region.
- Probability Density = probability per unit “length”.
 - Given an interval, we integrate the density over that interval to get the probability that the RV will be in that interval.



References

- From Discrete to Continuous Random Variables: [Y&G] Sections 3.0 to 3.1
- PDF and CDF: [Y&G] Sections 3.1 to 3.2
- Expectation and Variance: [Y&G] Section 3.3
- Families of Continuous Random Variables: [Y&G] Sections 3.4 to 3.5

Course Outline

The following is a tentative list of topics with their corresponding chapters from the text Yates and Goodman. Each topic spans approximately one week.

1. Introduction, Set Theory, Classical Probability [1]
2. Combinatorics: Four Principles and Four Kinds of Counting Problems [1]
3. Probability Foundations [1]
4. Event-based Conditional Probability [1]
5. Event-based Independence [1]
6. Random variables, Support, Probability Distribution [2]
7. **MIDTERM: 4 Oct 2018 TIME 09:00 - 11:00**
8. Discrete Random Variables [2]
9. Families of Discrete Random Variables and Introduction to Poisson Processes [2,10]
10. Real-Valued Functions of a Random Variable [2]
11. Expectation, Moment, Variance, Standard Deviation [2]
12. Continuous Random Variables [3]
13. Families of Continuous Random Variables and Introduction to Poisson Processes [3,10]

- [Excercise 15 Solution](#) [Posted @ 4:30PM on N
- [Excercise 16 Solution](#) [Posted @ 3PM on Nov
- [Slides](#) [Posted @ 4:30PM on Nov 6]
- Part IV: Continuous Random Variables
 - [Chapter 10](#) [Posted @ 10AM on Nov 5]
 - [Annotated notes for Sections 10.1–10.3](#) [Pos
 - References
 - From Discrete to Continuous Random
 - PDF and CDF: [Y&G] Sections 3.1 to 3.2
 - Expectation and Variance: [Y&G] Sectio
 - Families of Continuous Random Variab
- Part V: Multiple Random Variables

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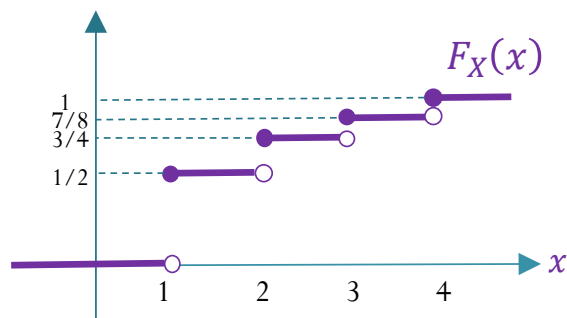
10.2 Properties of PDF and CDF

Sections 10.1-10.2

Discrete RV

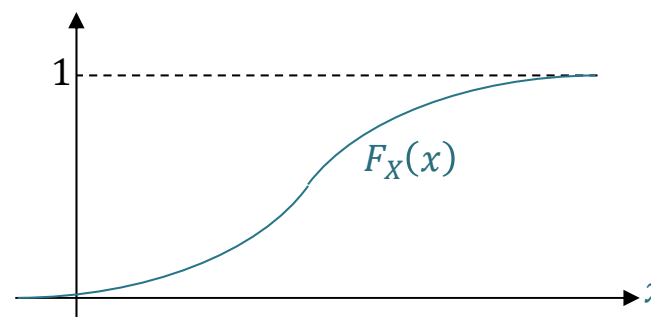
- **pmf**: $p_X(x) \equiv P[X = x]$
 - Two characterizing properties:
 - $p_X(x) \geq 0$
 - $\sum_x p_X(x) = 1$
- $S_X = \{x: p_X(x) > 0\}$
- $P[\text{some condition(s) on } X]$

$$= \sum_{\substack{\text{all the } x \text{ values that} \\ \text{satisfy the condition(s)}}} p_X(x)$$
- **cdf** is a staircase function with jumps whose size at $x = c$ gives $P[X = c]$.

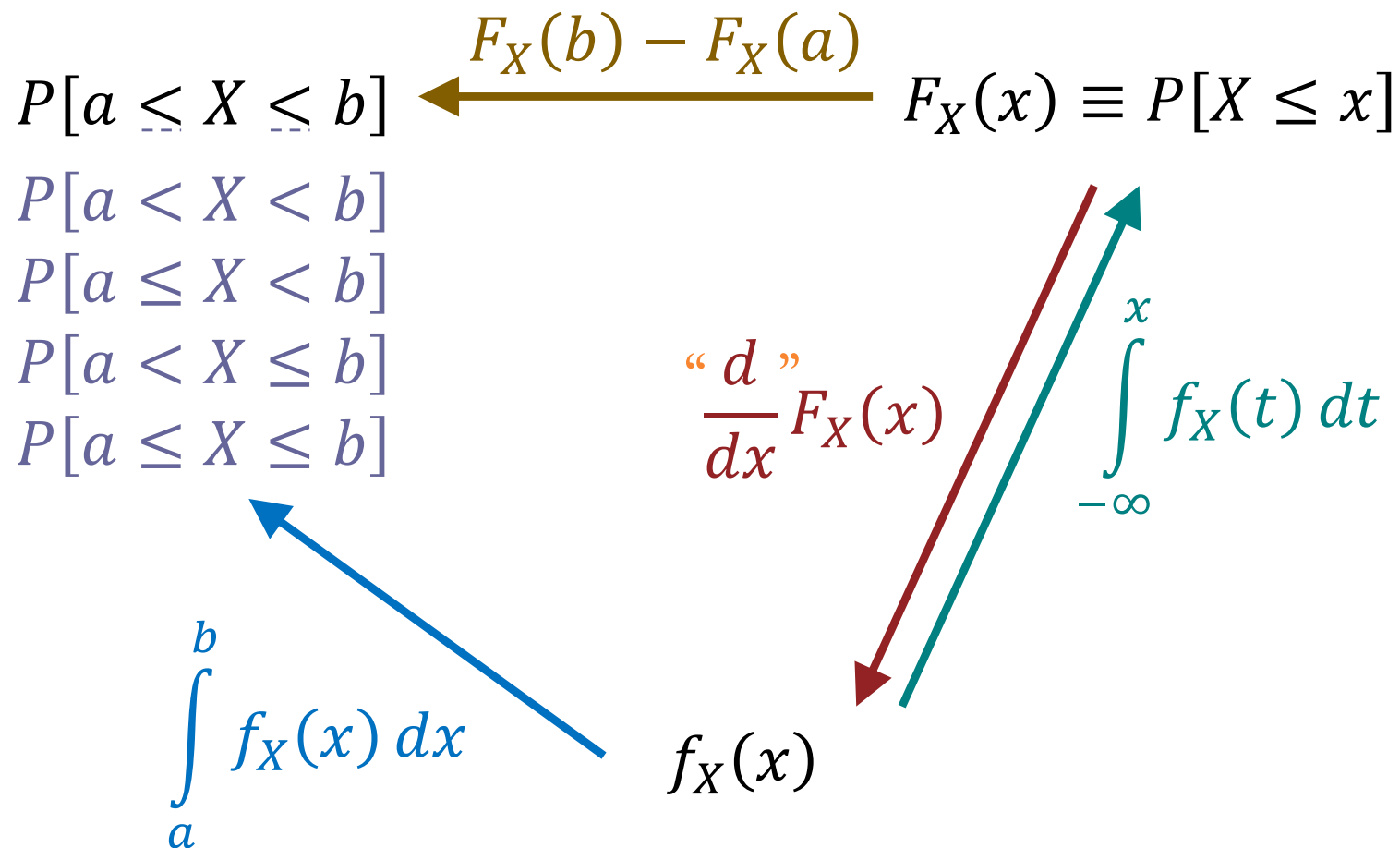


Continuous RV

- $P[X = x] = 0$
- **pdf**: $P[x_0 \leq x \leq x_0 + \Delta x] \approx \overbrace{f_X(x_0)}^{\text{probability per unit length}} \Delta x$
 - Two characterizing properties:
 - $f_X(x) \geq 0$
 - $\int_{-\infty}^{\infty} f_X(x) dx = 1$
- $S_X = \{x: f_X(x) > 0\}$
- $P[\text{some condition(s) on } X] = \int_{\substack{\text{all the } x \text{ values that} \\ \text{satisfy the condition(s)}}} f_X(x) dx$
- **cdf** is a continuous function.



pdf and cdf for continuous RV



Finding Probabilities from CDF

Definition: $F_X(x) \equiv P[X \leq x]$

For **any RV**,

- $P[X \leq b] = F_X(b)$
- $P[X > a] = 1 - F_X(a)$
- $P[a < X \leq b] = F_X(b) - F_X(a)$
- $P[X = a] = F_X(a) - F_X(a^-)$
(amount of jump in the CDF @ a)

For **continuous RV**,

- $P[X \leq b] = F_X(b)$
 $P[X < b] = F_X(b)$
- $P[X > a] = 1 - F_X(a)$
 $P[X \geq a] = 1 - F_X(a)$
- $P[a < X \leq b] = F_X(b) - F_X(a)$
 $P[a < X < b] = F_X(b) - F_X(a)$
 $P[a \leq X < b] = F_X(b) - F_X(a)$
 $P[a \leq X \leq b] = F_X(b) - F_X(a)$
- $P[X = a] = 0$



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10.3 Expectation and Variance

Chapter 9 vs. Section 10.3

Discrete RV

Continuous RV

$$\mathbb{E}X = \sum_x xp_X(x)$$

$$\mathbb{E}X = \int_{-\infty}^{\infty} xf_X(x)dx$$

$$\mathbb{E}[g(X)] = \sum_x g(x)p_X(x)$$

$$\mathbb{E}[g(X)] = \int_{-\infty}^{\infty} g(x)f_X(x)dx$$

$$\mathbb{E}[X^2] = \sum_x x^2 p_X(x)$$

$$\mathbb{E}[X^2] = \int_{-\infty}^{\infty} x^2 f_X(x)dx$$

$$\text{Var}[X] = \mathbb{E}[(X - \mathbb{E}X)^2] = \mathbb{E}[X^2] - (\mathbb{E}X)^2$$

$$\sigma_X = \sqrt{\text{Var}[X]}$$



Probability and Random Processes

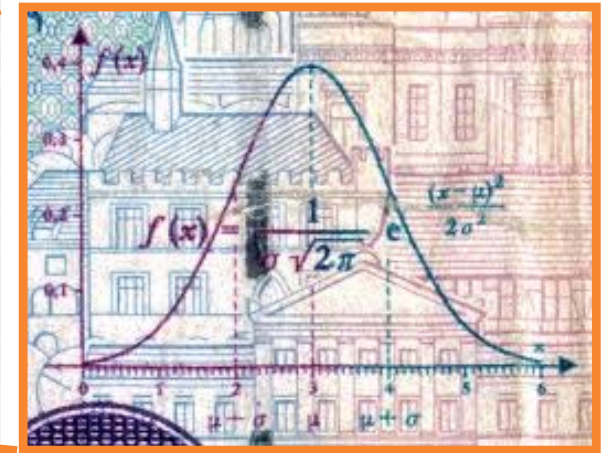
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10.4 Families of Continuous Random Variables

Johann Carl Friedrich Gauss



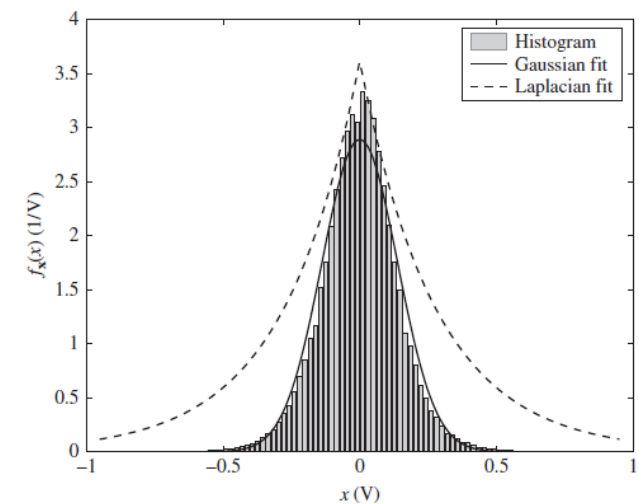
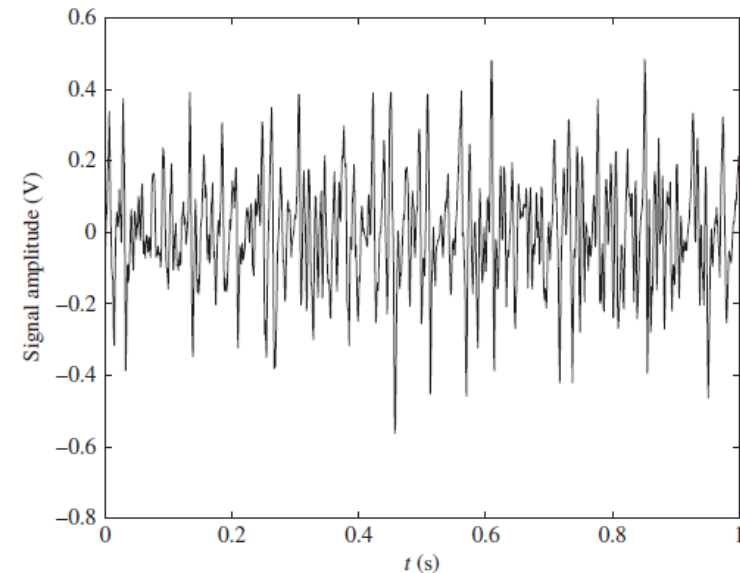
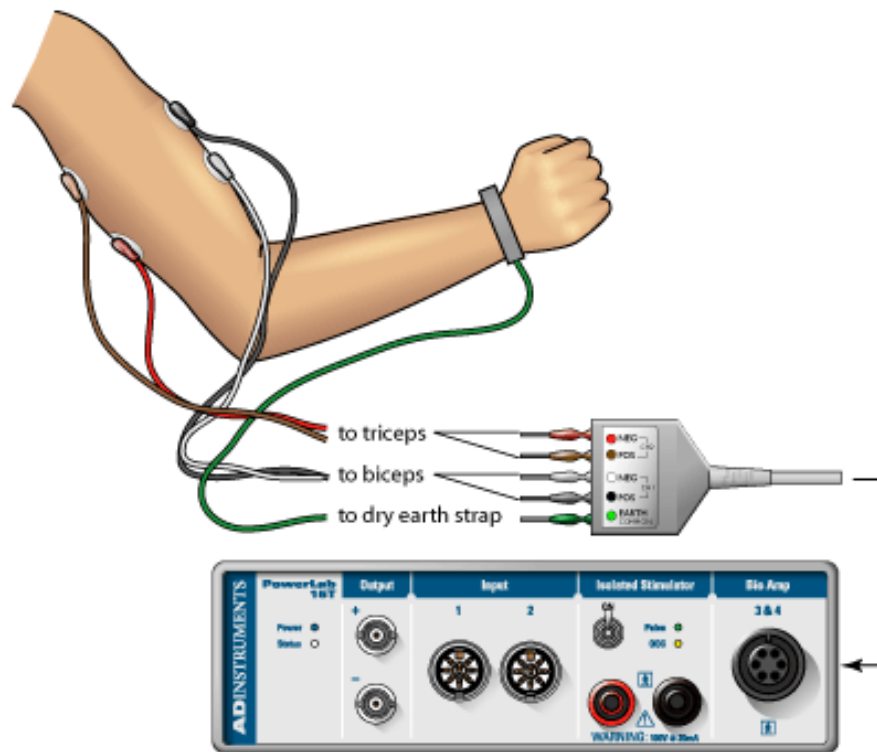
German 10-Deutsche Mark Banknote (1993; discontinued)

- 1777 – 1855
- A German mathematician



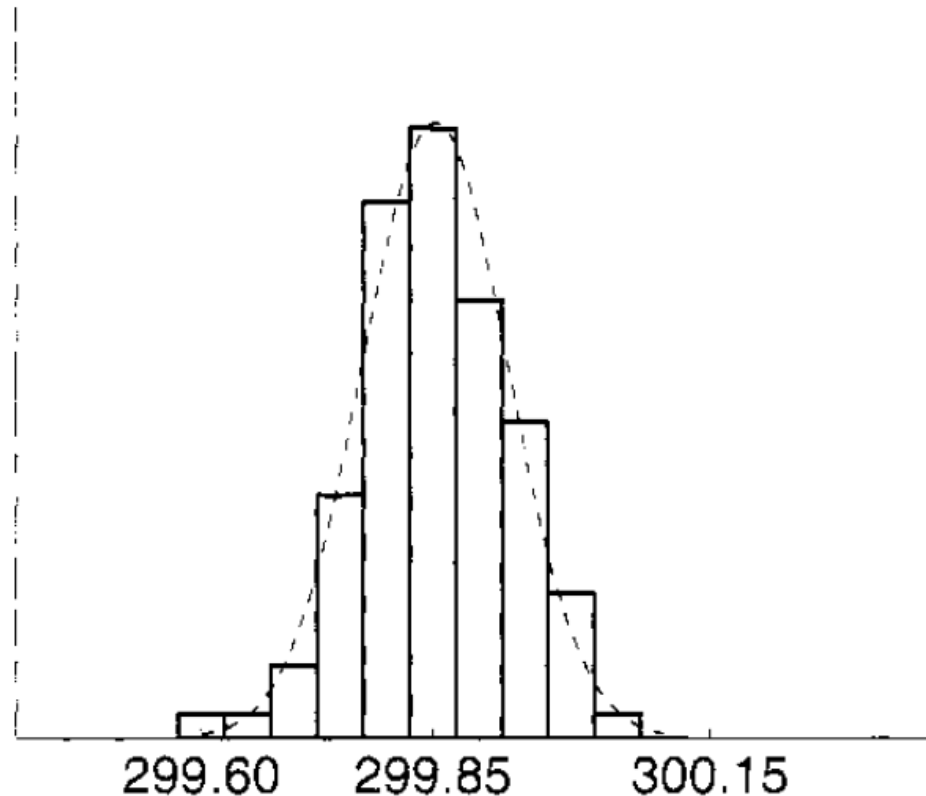
Ex. Muscle Activity

- Look at electrical activity of skeletal muscle by recording a human electromyogram (EMG).



Ex. Measuring the speed of light

- 100 measurements of the speed of light ($\times 1,000$ km/second), conducted by Albert Abraham Michelson in 1879.



Expected Value and Variance

“Proof” by MATLAB’s symbolic calculation

```
>> syms x
>> syms m real
>> syms sigma positive
>> int(1/(sqrt(sym(2)*pi)*sigma)*exp(-(x-m)^2/(2*sigma^2)),x,-inf,inf)
ans =
1
>> EX = int(x/(sqrt(sym(2)*pi)*sigma)*exp(-(x-m)^2/(2*sigma^2)),x,-inf,inf)
EX =
m
>> EX2 = int(x^2/(sqrt(sym(2)*pi)*sigma)*exp(-(x-m)^2/(2*sigma^2)),x,-inf,inf)
EX2 =
-(2^(1/2))*(limit(- x*sigma^2*exp((x*m)/sigma^2 - m^2/(2*sigma^2) - x^2/(2*sigma^2)) - m*sigma^2*exp((x*m)/sigma^2 - m^2/(2*sigma^2) - x^2/(2*sigma^2)) -
(2^(1/2)*pi^(1/2)*sigma*erfi((2^(1/2)*(x - m)*i)/(2*sigma))*(m^2 + sigma^2)*i)/2, x == -Inf) - limit(- x*sigma^2*exp((x*m)/sigma^2 - m^2/(2*sigma^2) -
x^2/(2*sigma^2)) - m*sigma^2*exp((x*m)/sigma^2 - m^2/(2*sigma^2) - x^2/(2*sigma^2)) - (2^(1/2)*pi^(1/2)*sigma*erfi((2^(1/2)*(x - m)*i)/(2*sigma))*(m^2 +
sigma^2)*i)/2, x == Inf))/(2*pi^(1/2)*sigma)
>> EX2 = simplify(EX2)
EX2 =
m^2 + sigma^2
>> VarX = EX2 - (EX)^2
VarX =
sigma^2
```

